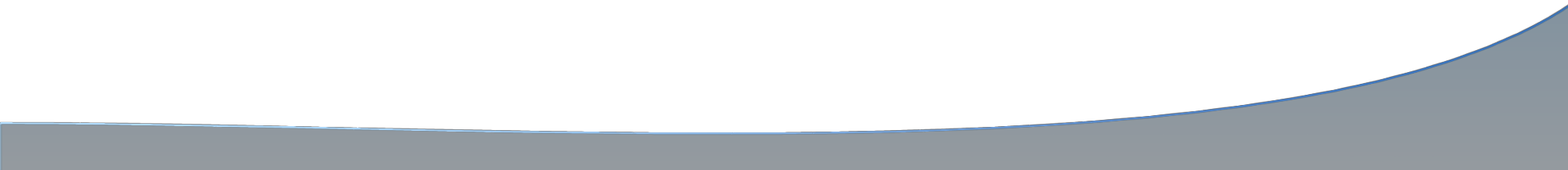


**C18 ZIP PERDE MOTORU**

Zip perde uygulamaları için elektronik limit swichli dahili alıcılı motor

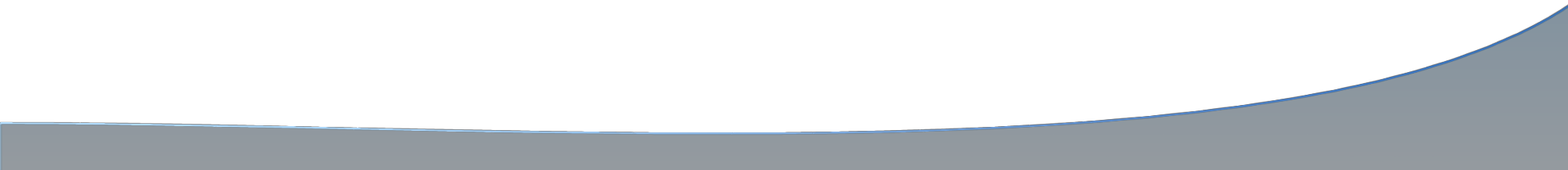
# Model ve Torklar



7

|  |  |  |
| --- | --- | --- |
| **Ürün** | **Tork (Nm)** | **Dönüş Hızı(1/min)** |
| R8-C01 | 8 | 17 |
| R12-C01 | 12 | 17 |
| R20-C01 | 20 | 17 |
| R30-C01 | 30 | 17 |
| R40-C01 | 40 | 17 |

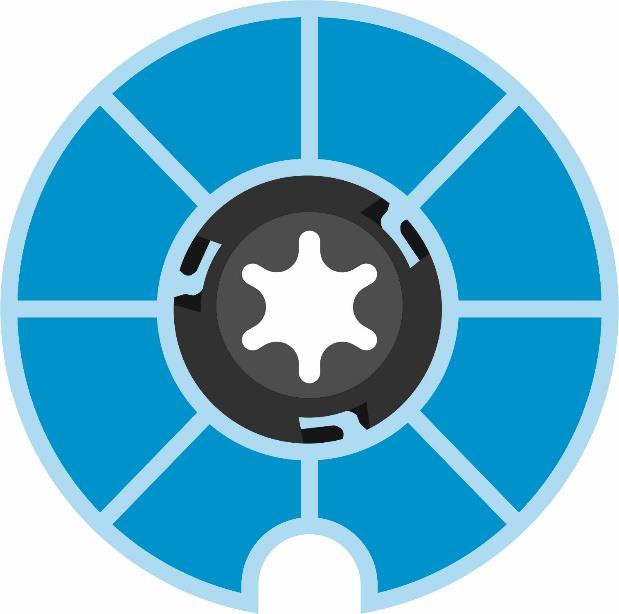
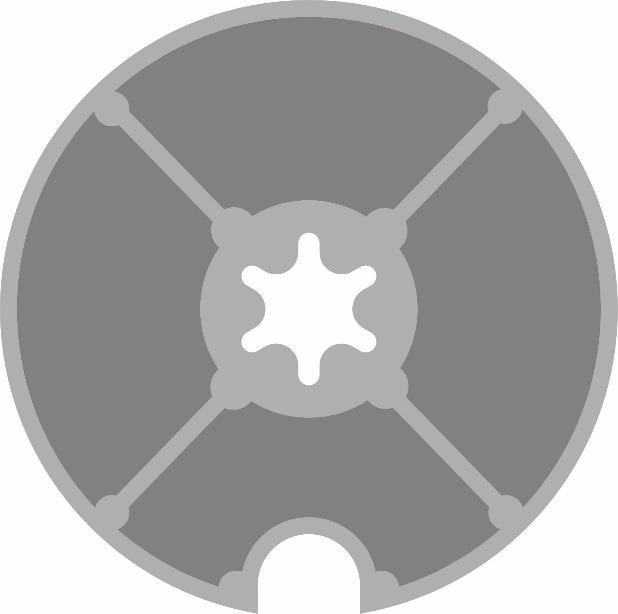
## Hassas Engel Tanıma Adaptörü

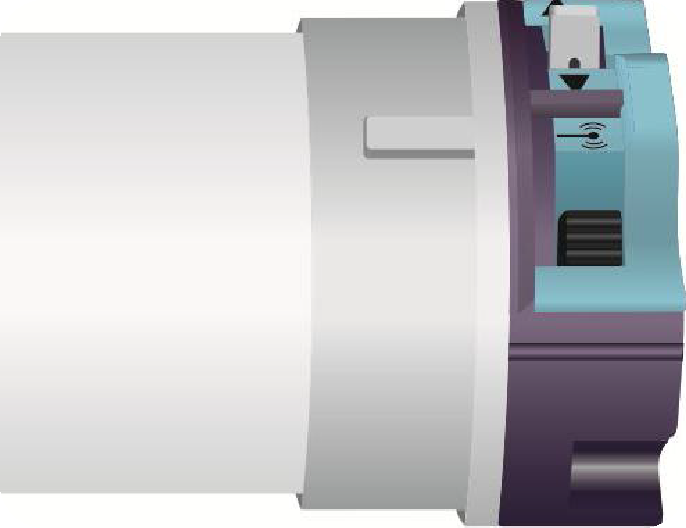
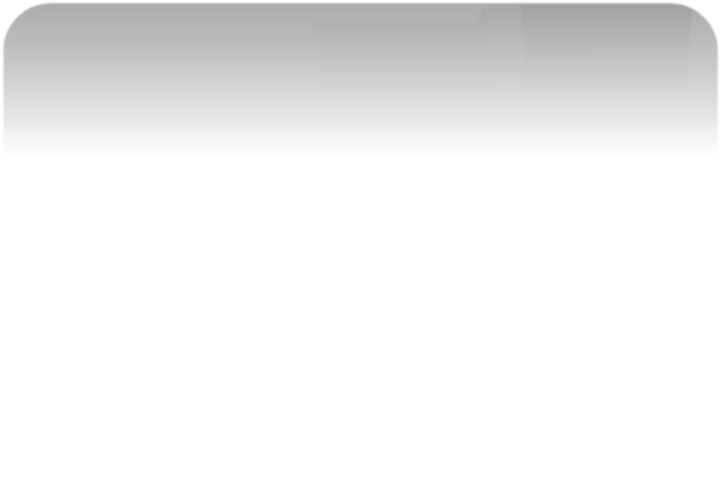
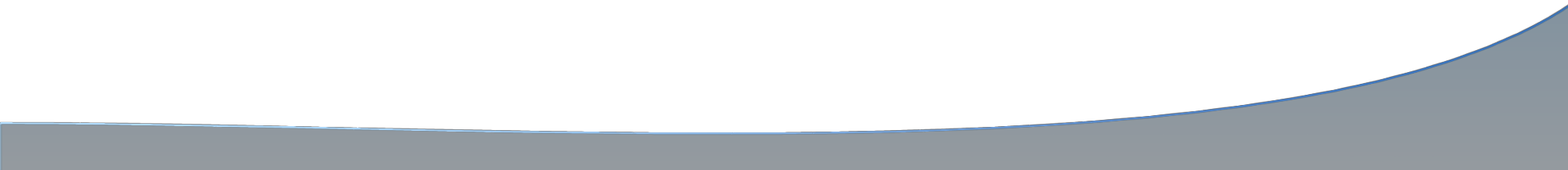


9

Normal Motor Adaptörü Hassas Engel

Tanıma Adaptörü





* Sessiz çalışır
* Güçlü kablosuz iletişim (868MHz) uzun mesafeler için

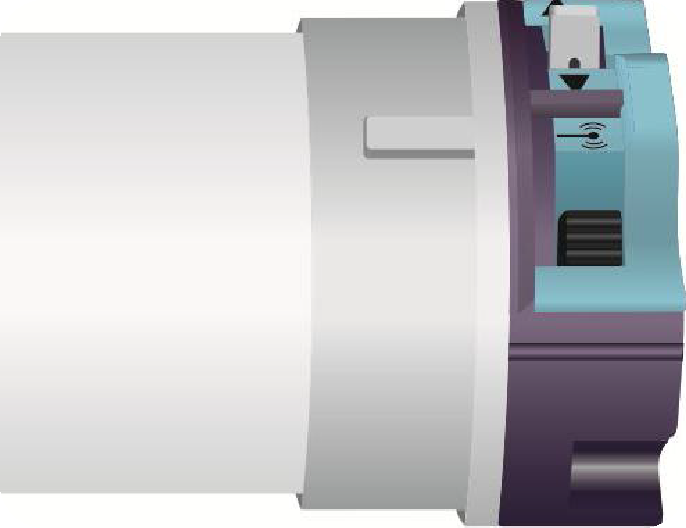
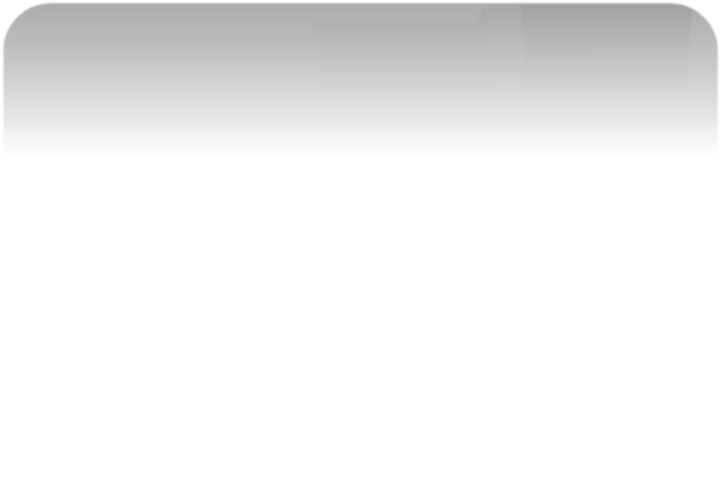
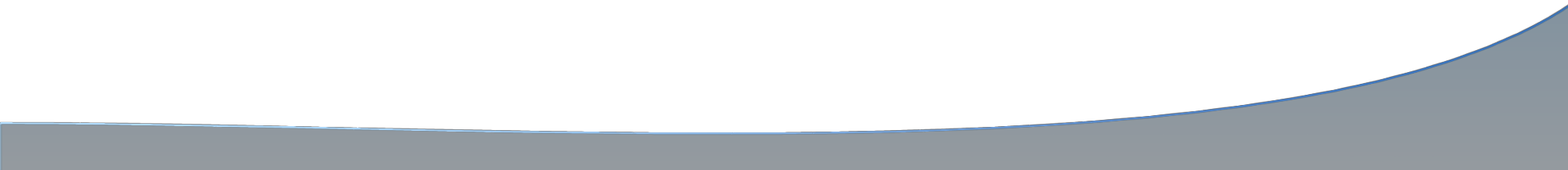
(açık alanda 350m)

* Kolay Kurulum ve

kablolama (220V yeterli)

* Kurulum için buton veya kumanda yeterlidir
* Otomatik swich ayarı
* Açılma yönünde sıkışma algılar

10



* Hassas engel tanıma

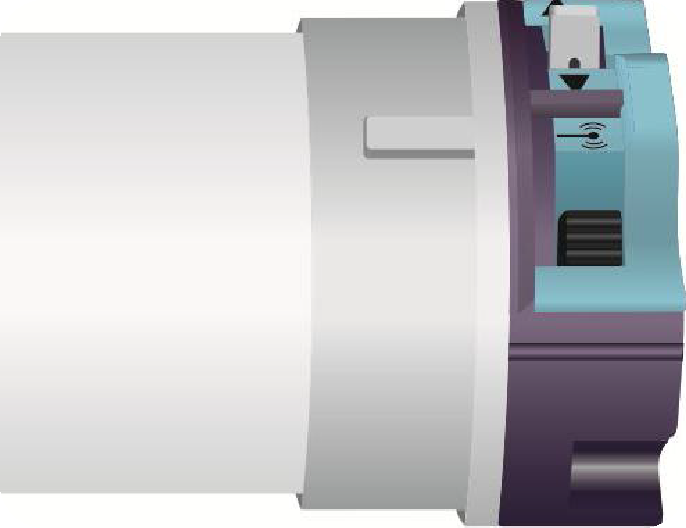
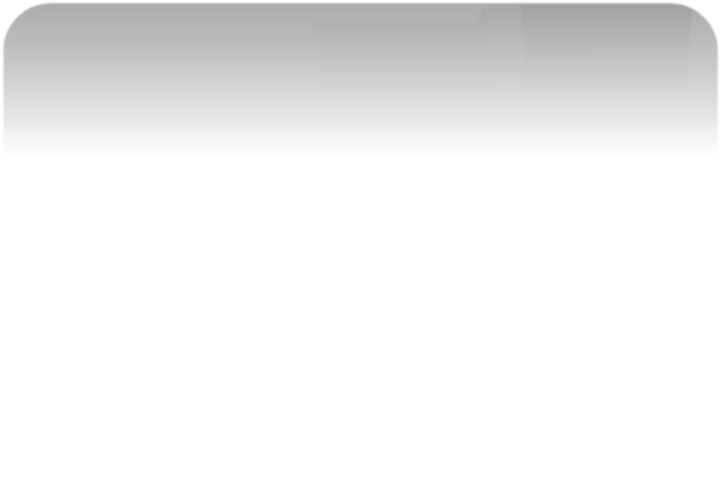
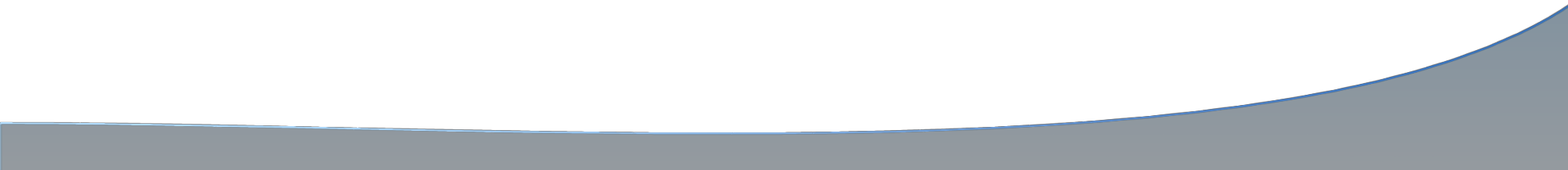
fonksiyonu.

* Üst limitte otomatik gerginlik ayarı
* Otomatik perde uzunluk ayarı
* Mekanik push buton

bağlanabilir

* Dinamik tork kontrolü

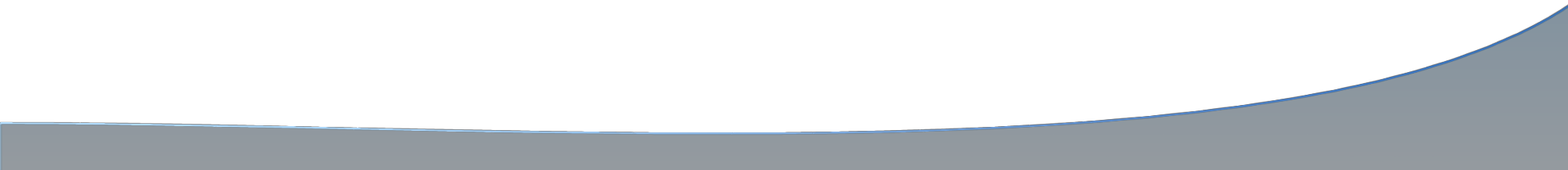
11



* Kolay Kurulum

12

## Aşağı yönde harekette hassas engel tanıma



\* Only using the obstacle detection drive adaptor

13

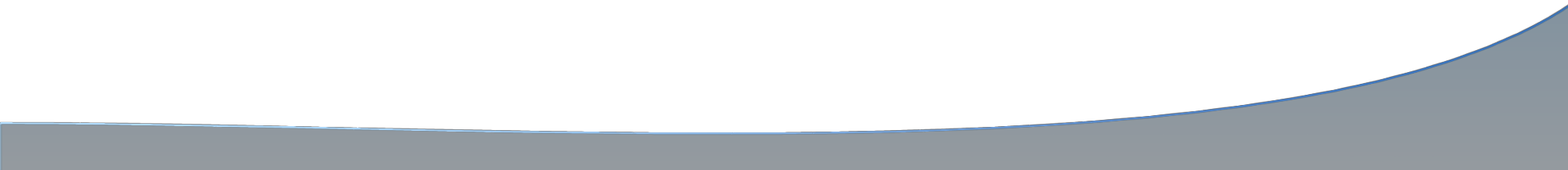
* Engeli otomatik algılar ve geri döner



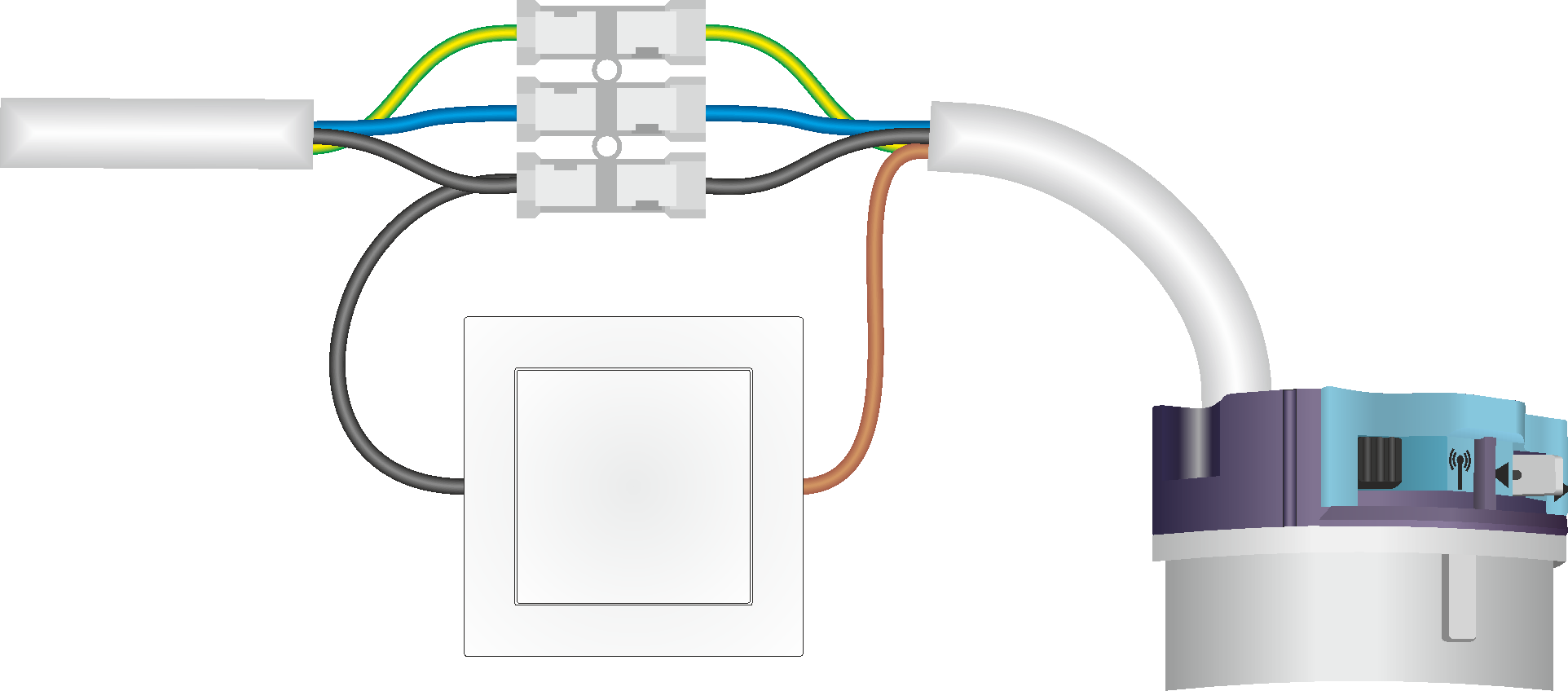
3x

* Rüzgarı algılamak için çoklu test yapar.(3 defa)

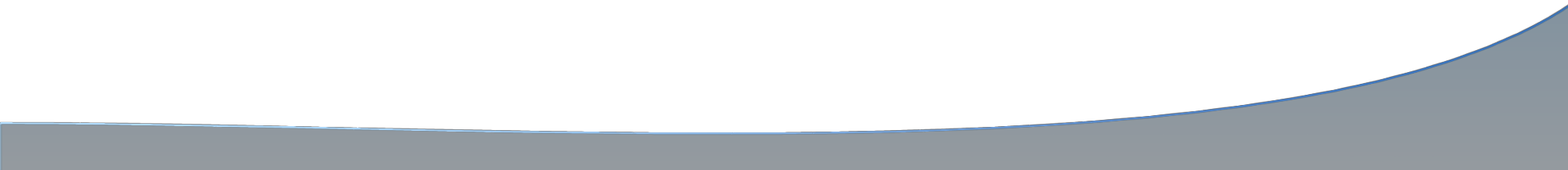
# Push buton bağlantısı



14

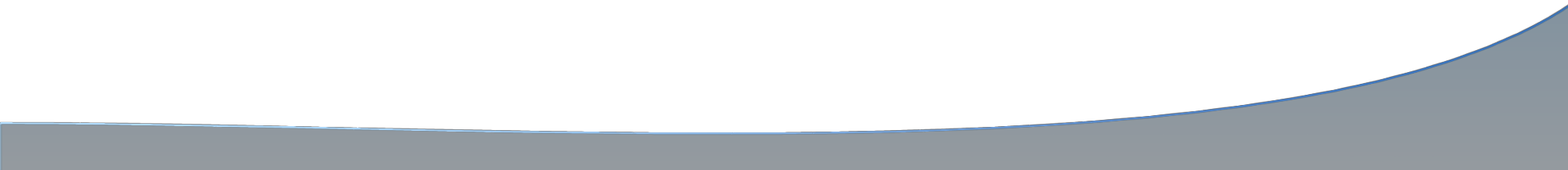


Kurulum



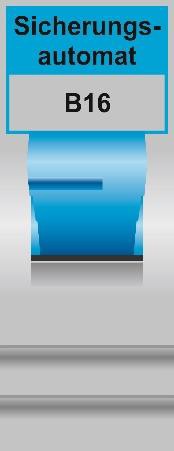
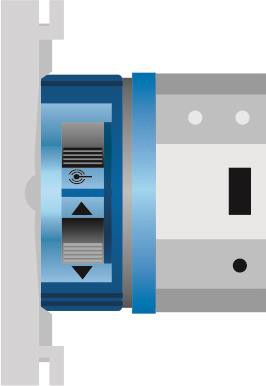
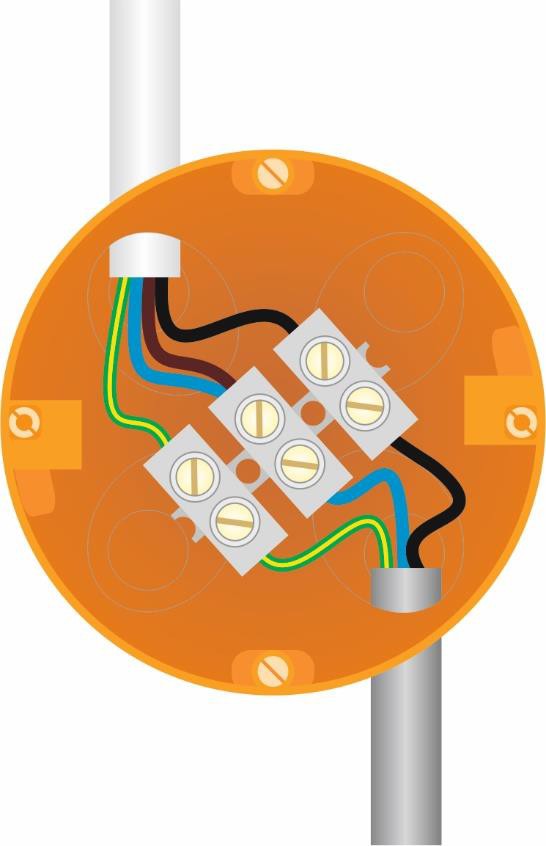


17



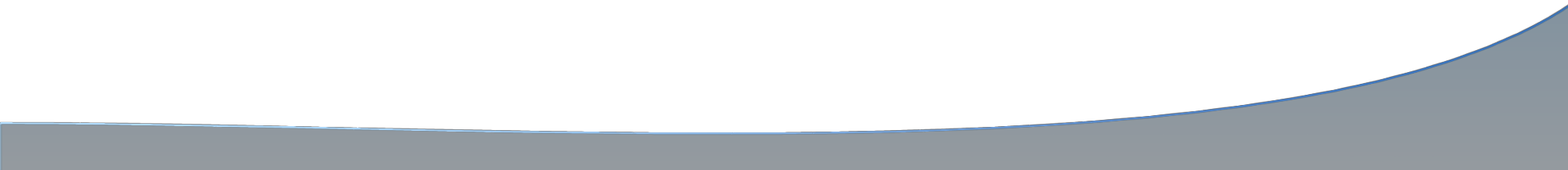
18

* Motora elektrik ver.



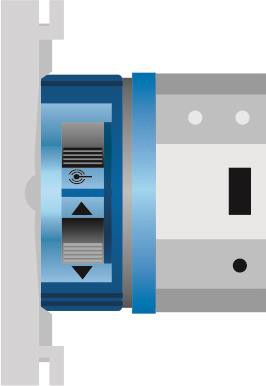
* 3 dk. Geçmeden kumandanın sağ yanındaki program

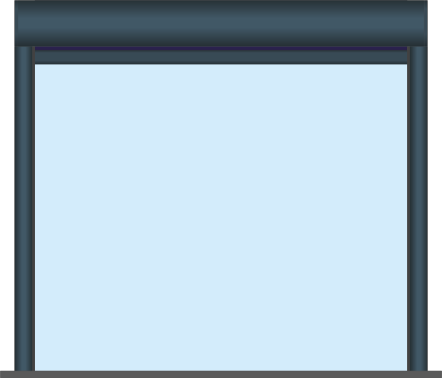
tuşuna motordan çift klik sesi gelene kadar basılı tut.



19

* Motoru hareket ettirin çalışma yönü ters ise gri tuşu çevirerek çalışma yönünü değiştirin.



1.  Motor kendi durana

kadar yukarıya çıkartın.

* + Motor kendi durana kadar aşağıya indirin.

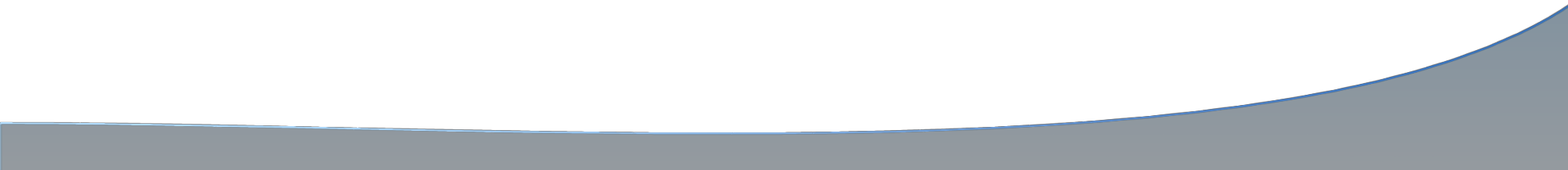
**2. 3. 4.**



Motor yukarı hareket eder aşağıya iner ve 5 sn. sonra klik sesi verir.

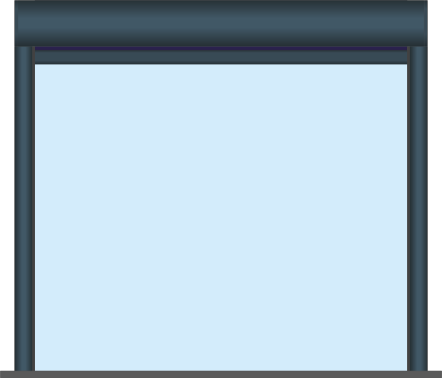
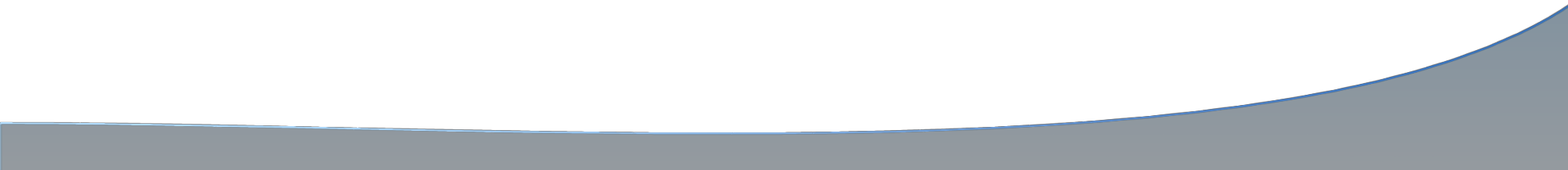
Swich ayarı

tamamlanmıştır.



* requires obstacle detection drive adaptor or rigid connectors

20



* + Alt limite getirip durudurun



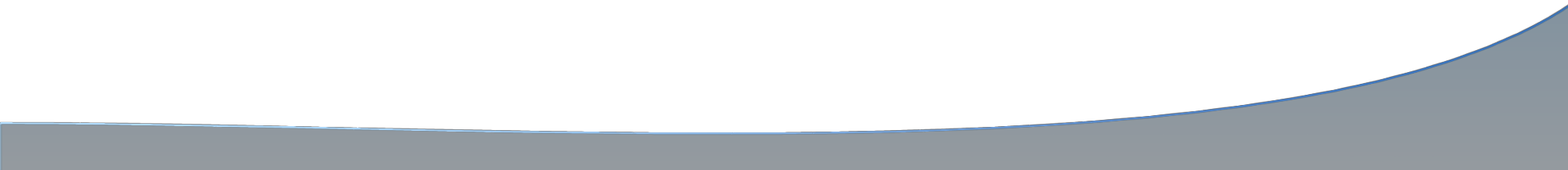
* + Klik sesi gelene kadar

Program ve Aşağı

tuşuna basılı tutun

* + Motor yukarıya çıkmaya başlayacak ve üst limitte otomatik duracaktır.

21



22

* + Motoru orta konuma getirin



* + Program ve durdurma tuşuna aynı anda klik sesi duyana kadar basılı tutun.